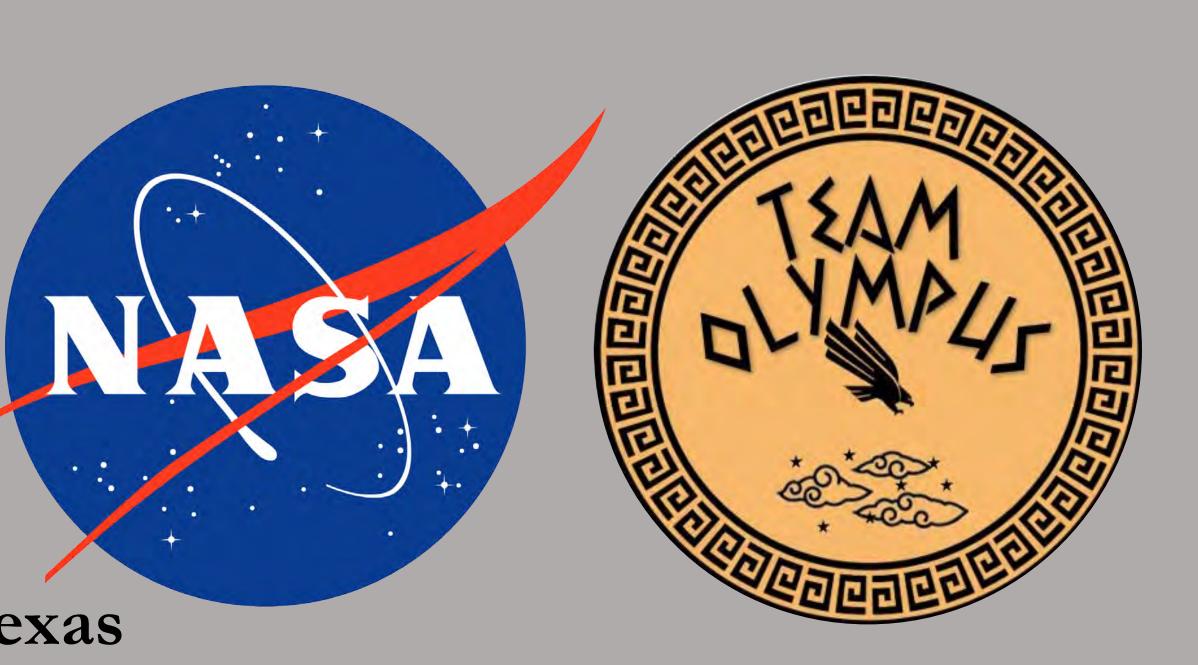


Private Cloud With Wireless Internet Of Things (IoT)

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Background

- In each mission, sensors have taken data periodically or episodically and create many data streams of importance which must rely on the current space communication architecture.
- Current space communication architecture is characterized by anemic on-board processing platforms and the bottleneck and latency in the backhaul to Earth.

Objective

The objective of this project is to:

- Examine an open source private or proprietary IoT cloud package and evaluate one through demonstration.
- Create a private cloud network that collects and process data from sensors through a microcontroller.
- Create applications that demonstrate the ability of the cloud to process sensor data and actuate certain output devices.
- Have a IoT cloud package that allows the user the ability to view and analyze current and past sensor data

Design

The Design for the Cloud Service

- The IoT Cloud Package used in this project is ThingBoard.io running on a general purpose computer in CentOS 7.
- The sensor data is taken from a Raspberry Pi 4 and then sent through a ASUS Router to the general purpose computer using MQTT protocol. The user can then create and view graphs that display the real time data.

Smart Door and Vivarium Application

- ThingsBoard.io will send an RPC call to the Raspberry Pi when it detects a human hand, or when it needs to adjust the vivarium's environment.
- The RPC call goes out when there is a notable difference in distance, temperature, and motion inside the smart door's entry way. With the vivarium a different RPC call goes out when there is a change in light, temperature, or humidity that adjusts the environment of the vivarium.

System Diagram ASUS Router Raspberry PI 4 Temperature Sensor Temperature Sensor Temperature Sensor Temperature and Humidity Sensor PIR Sensor TFT Touch Screen Mist Acomizer Cooler Module

Implementation



Figure 1: Model of the Smart Door

The cloud system and sensors are used in a smart door application to detect and when someone goes through the door on a smaller scale. The cloud system is also used to self adjust an environment in a vivarium.

Figure 1. shows the smart door and the placement of the sensors.

Figure 2. shows the vivarium that the second application monitors.



→ Wireless

System Components

General Purpose Computer

• 2 TMP006 Sensors

• 1 TFT Touch Screen

• 1 Ultrasonic Sensors

Humidity Sensor

Cooler Module

Atomizer

• 1 HTU21D-F Temperature &

• 1 VEML7700 Lux Sensor

• 1 Peltier Thermo-Electric

Atomization Maker Mist

• 1 WHDTS Ultrasonic

• 2 Raspberry PI 4

• 1 ASUS Router

• 1 PIR Sensor

Connection

Connected

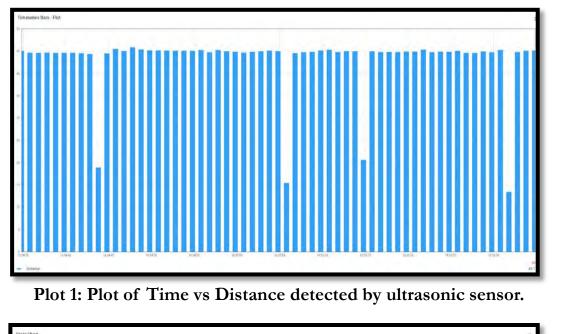
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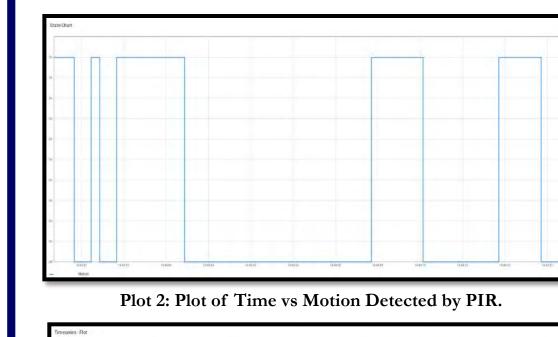
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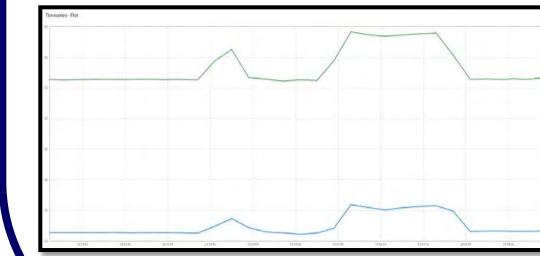
SPI

Figure 2: The Vivarium

Telemetry of ThingsBoard







Plot 3: Plot of Time vs Temperature Detected by TMP006.

With ThingsBoard we tested each sensor and graphed the data for each scenario. ThingsBoard can show each one with bar graphs, analog signal graphs, and line graphs. These are some of the graphs from application 1.

Plot 1 shows the distance detected by the Ultrasonic Sensor.

Plot 2 is the analog graph for the PIR motion values over time.

Plot 3 is the line graph that shows the current trend of the temperature being picked up by the TMP006.

Conclusion and Future Work

We have found a working IoT platform that supports a private network along with creating a private network the uses MQTT protocol to allow a microcontroller to connect, send, and receive data from ThingsBoard. The current system allows a user to connect a microcontroller to the private network and connect to ThingsBoard.io with MQTT protocol. We have also created two different case studies for ThingsBoard where we tested a passive system that can be used to self-sustain a closed environment and an active system that test how ThingsBoard reacts to controlled actions.

For future development with ThingsBoard a team would be able to implement remote connections to the private ThingsBoard network. This would allow the team to simulate the connection between a team on Earth connecting to a closed system in space.

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